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# Application of remote sensing in inland excess water research



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Szegedi Tudományegyetem Természeti Földrajzi és Geoinformatikai tanszék



## Természeti Földrajzi és Geoinformatikai tanszék



DOKTORANDUSZOK

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HALLGATÓKNAK

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ALUMNI

KIADVÁNYOK

KONFERENCIÁK

MÉDIASZEREPLÉSEK

www.aeo.u-szeaed.hu

"Fábián Tamással a világban" - Fotókiállítás

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III. JAKUCS LÁSZLÓ KÖZÉPISKOLAI FÖLDRAJZVERSENY 2013/2014

#### FELHÍVÁS!

A Szegedi Tudományegyetem TTIK Természeti Földrajzi és Geoinformatikai Tanszéke meghirdeti a

III. Jakucs László Középiskolai



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## Contents

- Introduction
- Inland excess water theoretical background
- Mapping of inland excess water
- Artificial neural networks method
- Results



# Inland access water (belvíz) problem

March 2006

Ninland excess water is a phenomenon where water temporarily remains in local depressions because of a surplus of water due to a combination of lack of runoff, insufficient evaporation and low infiltration capacity of the soil or because of upwelling of groundwater.







March 2005

ATIVIZIG: www.vizugy.hu



# Types of inland excess water

- Horizontal accumulative
  - On the surface
  - Source is precipitation
  - Closed depressions
- Vertical upwelling
  - Edge of alluvial fans
  - Source is (high) ground water level
- Queuing up
  - In front of pumping stations
  - Along channels
  - Due to insufficient pumping capacity



## Factors involved in inland excess water

**Snatially vary** 

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Inland excess water = f(M,R,S,Gr,L,Ge,A,...)

- Meteorology
- Relief
- Soil
- Groundwater
- Landuse
- Geology
- Antropogenic factors

# Meteorology



- Precipitation
- (Evapo-)transpiration
- Air temperature, wind speed

# Relief and geomorphology





#### RapidEye FCC, 2011

- Very small relief difference
- Local depressions
- Former river arms

#### Rakonczai et al. 2011



# Lithology and groundwater



## Landuse

- Build up type
- Infiltration
- Run off





# Other antropogenic factors



- Channels
- Pumping stations
- Levees
- Roads, rail roads

# Possibilities for reduction and mitigation

and the same

### The key questions:

- to *locate* inland excess water
- to understand the *formation* of the inundations
- to find the possibilities for *intervention*

# Methods: 1. Vulnerability mapping



 $w_i = weight$  $T_i = factor$ 

## Pálfai map 1:500 000



## Methods: 2. In situ mapping -Field measurements



# Methods: 2. RS based mapping

• Classification based on reflectance data of satellite images or digital aerial photographs





Rakonczai et al. 2001

# Generation of RS based inland excess

### water maps

• Remote sensing data acquisition







- Geoinformatics processing techniques
  - Index based
  - Classification based
  - Segmentation

# TFGT Data collection system



# Inland excess water mapping

- Field observations
  - Financial constrains
  - Time consuming
  - Error prone
- Aerial photography
  - Financial constrains
  - Time consuming
- Satellite imagery
  - Spatial resolution
  - Temporal resolution
  - Coverage



# Processing of RS data

- Visual interpretation
- Indexing
- Classification
- Modelling



## Index based water detection



Reclassified NDVI values derived from a MODIS satellite image (Baksa 2012). Wetness band of a Tasseled cap transformed LANDSAT image (Baksa 2012).

# Traditional classifications

Landsat

• Multispectral satellite data

- ISODATA
- Box classifier
- Minimum distance
- Maximum likelihood



# Artificial neural networks (ANN)

- $\rightarrow$  Training
- $\rightarrow$  Weights
- $\rightarrow$  Activation
- $\rightarrow$  Simulation
- Advantages
  - Robust
  - Non linear system
  - Huge data amounts
- Disadvantages
  - Difficult to understand what exactly happens
  - Calculation intensive



Determination of the weights is an integral part of the training

# Study area

- Inland excess water occurrences
- Earlier scientific research TFGT
- Close to the local airport





# Data

- Local depressions derived from LIDAR DEM
- Color InfraRed digital aerial photographs
- Anthropogenic objects
- Soil map
- Fieldwork











## ANN – GIS Framework



## Results



#### First experiment:

4 input layers. Training area (left) with the GPS fieldwork result and the simulation area (right)

#### Training result: R = 0.74

## Simulation results – 2 different dates

#### 24 March 2010

### 9 June 2010



# Results

- 3 classes
  - Open water
  - Saturated soil
  - Dry land



# Influence of the input layers

- A. 4 input layers
- B. 5 input layers
- C. 8 input layers
- D. 9 input layers



B

	4 inputs	5 inputs	8 inputs	9 inputs
Cohen's Kappa (ĸ)	0,76	0,81	0,86	0,83
Overall accuracy (%)	88	91	93	91

# Comparison with traditional classifications



Minimum distance

#### Maximum likelihood

Artificial neural network

- 2 classes
- 3 input layers (CIR bands)

# Maximum likelihood

- 7 osztály
- 6 non-water classes merged into one class





# Results

	Correctly	Correctly	Total	Total	Overall
	classified	classified	water	non-	accuracy
	water	non-	found	water	
		water			
MD based on 2 classes	119	83	186	114	67 %
ML based on 2 classes	135	72	213	87	69 %
ML with merged non- water classes	90	120	120	180	70 %
ANN two classes (3 layers)	93	128	115	185	74 %
ANN two classes (8 layers)	149	130	169	131	93 %

# Artificial neural network

- ANN 2 classes
- 20 hidden neurons
- 8 layers:
  - 3 CIR
  - Local depressions
  - Channels
  - Buildings
  - Roads
  - Wells



# Thank you for your attention

#### Boudewijn van Leeuwen

#### http://www.geo.u-szeged.hu/meriexwa

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